

OBSERVATIONAL ASTRONOMY

AUTUMN 2024

Lecture 9 Vitaly Neustroev

Physical limitations on the precision of photometric measurements (6)

 \Box In dark sky at a dark site (no moon, no reflected street light), the magnitude of a 1 arcsecond patch of sky in the *V* band is approximately V_{sky} =21.5 mag.

> Thus, every square arcsecond of sky gives: $S_{sky} = 2.5 \times 10^{-3}$ photons / (cm² arcsec² second)

Physical limitations on the precision of photometric measurements (7)

- To calculate the *Output* **Signal-To-Noise Ratio** of an observation we need to know the signal, and all sources of noise. These are:
	- **Photon noise (shot noise) from the signal;**
	- **Photon noise from the sky background under the signal;**
	- **Photon noise from the sky background measurement to be subtracted off;**
	- **Readout noise from all sources;**
	- **E** Fixed pattern noise;
	- **□ Bias noise;**
	- Dark current noise.

A case study of simple aperture photometry (1)

- □ We observe a star on a CCD detector, and process the data in the simplest way possible.
- An area centred on the star is defined to be the object area and is large enough to contain all the photons from that star.
- □ An equal area some distance away, which is found to be free of stars, is defined as the sky background area (sky aperture), and the sky background is measured from that.

A case study of simple aperture photometry (2)

355

We will make some assumptions:

■ We have eliminated fixed pattern noise by dividing the image by a normalised long exposure of a uniform light source, this is called *a flat field*.

□ Bias noise and dark current noise are negligible, as this is a cryogenically cooled, buried channel CCD.

Aperture photometry

 \Box There are a number of parameters we need to take into account to calculate the signal which reaches the detector:

t – exposure time

- \Box β angular size of a source (defined by the seeing)
- **□** D diameter of the telescope
- S_{sky} [photons / (cm² arcsec² second)] brightness of the sky
- *η* quantum efficiency of a detector (QE)
- **□** f_* [photons / (cm² second)] the source flux to be measured

Signal calculation (1)

- \Box We start from the number of photons incident from this star, from the sky, and from the star $+$ the sky: $\Box A \sim D^2$ is the telescope collecting area [cm²] \Box *B* \sim β ² is the source area on the sky [arcsec²]
- *n*[∗] ≈ *η D*² *t f*^{*} − an average number of photons from the source n_{sky} ≈ *η D² t* β² S – an average number of photons from the sky *n**+sky *η D² t (f* +*β ²*S) –* an average number of photons from the source and the sky

Signal calculation (2)

- \Box That is without the Readout noise and other detector noises. If we want to take them into account – we must add N_d = n_d *t* to the right side of equations.
- \Box There is also a geometric efficiency factor as part of the aperture of the telescope is blocked by the secondary mirror.

For a while, we will not take these factors into account.

Noise on the measurements

359

 \Box Noise on the measurements is given by the square root of the number of photons:

$$
\sigma_{*+{\rm sky}}=\sqrt{n_{*+{\rm sky}}}
$$

$$
n_* \approx n_{*+sky} - n_{sky}
$$

$$
\sigma_* = \sqrt{n_{*+sky} + n_{sky}} = \sqrt{n_* + 2n_{sky}}
$$

(If x and y have independent random errors σ_x and σ_y , then the error in $z = x ± y$ is $\sigma_z^2 = \sigma_x^2 + \sigma_y^2$)

Signal to Noise ratio (1)

Let's now consider two special cases:

□ If the Source dominates over the Sky: \mathbf{n} \gg $\mathbf{n}_{\rm sky}$ If the Sky noise dominates: **nsky** ≫ **n***

Signal to Noise ratio (2)

361

$$
SN = \frac{n_*}{\sqrt{n_* + 2n_{sky}}} = \frac{\eta \, D \, t \, f_*}{\sqrt{\eta \, t \, (f_* + 2 \, \beta^2 \, S)}}
$$

If the Source dominates over the Sky: $n_* \gg n_{\rm sky}$

$$
S/N \cong \frac{n_*}{\sqrt{n_*}} = \sqrt{n_*} = D\sqrt{\eta \ t f_*}
$$

 $f_{\min} \sim 1$ / (D²*t*) for the given S/N the telescope aperture is most important!

Signal to Noise ratio (3)

362

If the Sky noise dominates: $n_{sky} \gg n_*$

$$
SNN = \frac{n_*}{\sqrt{n_* + 2n_{sky}}} = \frac{\eta \, D \, t \, f_*}{\sqrt{\eta \, t \, (f_* + 2 \, \beta^2 \, S)}}
$$

$$
S/N \cong \frac{n_*}{\sqrt{2n_{sky}}} = \frac{\eta D t f_*}{\sqrt{2\eta t \beta^2 S}} = \frac{D f_*}{\beta} \sqrt{\frac{\eta t}{2S}}
$$

$$
f_{\min} \sim \frac{\beta}{D} \sqrt{\frac{s}{t}}
$$
 for the given S/N
the seeing (angular size of a source) is most important!

Signal to Noise ratio (4)

Source dominates over the Sky Source dominates

$$
S/N \cong D\sqrt{\eta\ t f_*}
$$

$$
f_{\min} \sim \frac{1}{D^2 t}
$$

$$
S/N \simeq \frac{Df_*}{\beta} \sqrt{\frac{\eta t}{2s}}
$$

$$
f_{\min} \sim \frac{\beta}{D} \sqrt{\frac{s}{t}}
$$

for the given S/N

for the given S/N

the telescope aperture the seeing

most important is

³⁶⁴ Photometry

The technique that measures the relative amounts of light in different wavelength ranges.

Stellar magnitudes

365

Magnitudes:

 \Box Apparent magnitudes $m^{}_1 - m^{}_2 = -2.5 \log \frac{E^{}_1}{E^{}_1}$ E_{2} \blacksquare **Absolute magnitudes**

$$
M - m = -2.5 \log \left(\frac{D}{10}\right)^2
$$

D is the object's distance in parsecs

```
M = m + 5 - 5 \log DM = m + 5 - 5 \log D - A \cdot D
```
A is the interstellar absorption in magnitudes per parsec. Within the galactic plane A is \sim 0.002 mag pc⁻¹.

 \Box Sometimes M may be estimated by some independent method. Then:

$$
D = 10^{[(m-M+5)/5]} \text{ pc}
$$

Filters and photometric systems

\Box Filter (photometric) systems:

- **<u>n</u>** Filters are used to restrict the wavelengths of electromagnetic radiation that hit the detector.
- □ Why may we want to do that?
	- **E** Because stars have different colours that means they have different temperatures.

Observing through filters (1)

Hot objects emit most of their light at short wavelengths

Cool objects emit most of their light at long wavelengths

Observing through filters (2)

368

Observing through filters allows us to estimate temperatures.

Observing through filters (3)

Which are the three brightest stars?

Observing through filters (4)

Which are the brightest stars?

It depends on the bandpass through which one observes them.

Photometric systems

- There is a number of different **photometric systems**, each one based on a particular passband (i.e. a particular combination of filter and detector and telescope).
- \Box They may be grouped into wide, intermediate, and narrowband systems according to the bandwidth of their transmission curves. In the visible region:
	- \blacksquare Wide (broadband) filters have bandwidths of \sim 1000 Å
	- Intermediate: 100-500 Å
	- **□** Narrowband filters range from 0.5 to 100 Å.
- \Box One should always remember to specify the system when quoting the magnitude of a star.

Johnson-Cousins photometric system (UBVRI)

- Most astronomers working in the optical use the Johnson-Cousins **UBVRI** photometric systems:
	- Johnson and Morgan defines the **UBV** system with stars visible in the northern hemisphere
	- Cousins defines the redder **R** and **I** passbands.
- \Box The systems are defined by particular combinations of glass filters and photomultiplier tubes (they were created many years ago before CCDs existed). Since photomultipliers and CCDs have very different spectral sensitivities, it is difficult to make the effective passband of a CCD-based instrument match that of a photomultiplier-based instrument.
- □ In 1990, Michael Bessell came up with a recipe for making filters out of common colored glasses which would reproduce pretty closely the official Johnson-Cousins **UBVRI** passbands \rightarrow Bessell filters.

Johnson-Cousins photometric system

373

□ The spectral resolution of the broadband UBVRI passbands is small: $R = \lambda/\Delta\lambda \approx 5$

SDSS (ugriz) photometric system

- **374**
- □ Although UBVRI is the best known optical system, there are a number of others. Some were specifically designed to solve a particular astrophysical problem, others to mesh with particular detectors. One important system is the **u'g'r'i'z'** that is being used by the Sloan Digital Sky Survey (**SDSS**) and the Panoramic Survey Telescope and Rapid Response System (Pan-STARRS). It has become very popular recently.

Strömgren photometric system

375

 Strömgren photometric system (uvby) is four-colour intermediate-band photometric system (plus Hβ filters) for stellar classification. It was pioneered by the Danish astronomer Bengt Strömgren in 1956.

Strömgren filter set

Wavelength [nm]

Narrowband photometric systems

- **376**
- \Box For some applications, astronomers use narrowband filters; a common filter used to measure light emitted by hydrogen atoms is centered at 6563 Angstroms and roughly 20 Angstroms wide: $R = \lambda/\Delta\lambda \approx 330$
- \Box A narrowband filter like this requires much longer exposure times to build up the same signal as a broadband filter. Since telescope time is so precious, astronomers tend to use broadband systems. That's one reason for the popularity of the UBVRI or SDSS systems.

Photometric systems (optical)

The Infrared Photometric Bands: JHK+others

… where the atmospheric transmission windows are

Filter transmission curves (1)

379

- Typical broad-band transmission curves are **not** rectangular, and even **not** symmetric.
- \Box Different quantities can be used to describe a filter, e.g.:
	- \blacksquare λ_{c} is the wavelength halfway between the points, where the band transmission profile reaches half of the maximum value.
	- **D** WHM is the the full wavelength span between the points, where the band transmission profile reaches half of the maximum value.
	- \Box λ_{peak} is the wavelength at which the band transmission profile reaches its maximum.

From Fiorucci and Munari, 2003, A&A, 401, 781

Filter transmission curves (2)

- □ Some important parameters depend on the source spectrum. For example,
	- \blacksquare λ_0 is the mean wavelength of the band, the property of just a band:

$$
\lambda_{\circ} = \frac{\int \lambda F(\lambda) \, \mathrm{d}\lambda}{\int F(\lambda) \, \mathrm{d}\lambda}.
$$

u whereas the effective wavelength λ_{eff} is

$$
\lambda_{\text{eff}} = \frac{\int \lambda F(\lambda) S(\lambda) d\lambda}{\int F(\lambda) S(\lambda) d\lambda}
$$

where

- *F* (λ) is the transmission profile of the band, and
- *S* (λ) the energy distribution of a source spectrum.

Filter transmission curves (3)

Good sources of info:

- *The Asiago Database on Photometric Systems* (218 systems; checked on 2023-09-20)
	- <http://ulisse.pd.astro.it/Astro/ADPS>
	- Fiorucci and Munari, 2003, A&A, 401, 781
- *Filter Profile Service* (10625 filters available on 2023-09-20)
	- <http://svo2.cab.inta-csic.es/theory/fps/>

Magnitudes & Photometric systems

- \Box When writing the magnitude of a star, astronomers use an abbreviation to denote the photometric system of the measurement:
	- \blacksquare V = 1.03 (or 1.03V) means "magnitude of this star in the V system is 1.03"
	- \blacksquare B = 0.46 (or 0.46B) means "magnitude of this star in the B system is 0.46"

But a magnitude system can be different!

Magnitude systems

$$
m_1 - m_2 = -2.5 \log \frac{F}{F_0}
$$

The flux *F⁰* defines the reference or **zeropoint** of the magnitude scale. The choice is arbitrary.

- Standardizing magnitudes (magnitude systems):
	- **D** Vega system
	- **D** AB system
	- **D** ST Magnitudes

A magnitude system is **not** a photometric (filter) system (you can use a filter in any system)

Photometry: Vega system

- \Box Astronomers have chosen to use the bright star Vega (α Lyr) as their starting point.
- □ In the UBVRI systems, the star Vega is **defined** to have a magnitude of zero in all bands (actually, this is not quite true):

$$
U = 0.0; B = 0.0; V = 0.0; R = 0.0; I = 0.0
$$

- □ This means also that all the colours of Vega are zero.
- \Box The zero-point of this system depends on the flux of Vega (outside the atmosphere) and is different in different bands.

Photometry: AB system

- \Box In the $\overline{\mathsf{AB}}$ system, which is not based on Vega, it is assumed that the flux constant $\overline{\mathit{F}}_0$ is the **same** for all wavelengths and passbands.
- \Box That constant is per definition such that in the V filter: $m_V^{Vega} = m_V^{AB} = 0$ (or more accurately: F_{λ} dv $\equiv F_{\lambda}$ d λ when averaged over the *V* filter, or at the effective wavelength of the *V* filter, $\lambda_{\text{eff}} = 5480$ Å. Based on the work of Oke (1974), then

 $m_{\nu} = -2.5 \log F_{\nu} - (48.585 \pm 0.005)$

where $F_v(\lambda)$ is the spectral flux density per unit frequency of a source at the top of the Earth's atmosphere in units of erg s⁻¹cm⁻² Hz⁻¹.

 \Box Note that the AB magnitude system is expressed in $\mathsf c$ rather than $\mathsf F_{\lambda}!$

The flux density in $F_{\rm v}$ is related to the flux density in $F_{\rm \lambda}$ by:

$$
F_v
$$
 [ergs s⁻¹ cm⁻² Hz⁻¹] = 10⁻⁸ $\frac{\lambda[\mathring{A}]^2}{c \text{ [cm s$^{-1}$]}} F_{\lambda}$ [ergs s⁻¹ cm⁻² Å⁻¹]

□ One can easily convert between AB magnitudes and Janskys: In AB magnitudes, mag 0 has a flux of 3631 Jy.

AB and VEGA systems compared

□ The difference between AB and VEGA magnitudes becomes very large at redder wavelengths!

 \Box The spectrum of Vega is very complicated at IR wavelengths and often model atmospheres are used adding to uncertainties

